# An expository supplement to the paper "Optimization of the Gaussian and Jeffreys power priors with emphasis on the canonical parameters in the exponential family" 

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This article gives an expository supplement to Ogasawara (2014) for the estimators of the multinomial logits in the categorical distribution, which is the generalization of the Bernoulli distribution.

## 1. The Fisher information matrix

Define the likelihood of the vector of the canonical parameters $\boldsymbol{\theta}$ when $n$ observations are given as:

$$
\begin{equation*}
L=\prod_{i=1}^{n} \prod_{j=1}^{K} p_{j}^{y_{i j}} \tag{S.1}
\end{equation*}
$$

where $y_{i j}(i=1, \ldots, n ; j=1, \ldots, K)$ are given observations. Let $\bar{l}=n^{-1} \log L$. Then,

$$
\begin{align*}
& \frac{\partial \bar{l}}{\partial \theta_{j}}=\left.\frac{\partial \bar{l}}{\partial(\boldsymbol{\theta})_{j}}\right|_{\theta=\boldsymbol{\theta}_{0}}=n^{-1} \sum_{i=1}^{n} \sum_{a=1}^{K} \frac{y_{i a}}{p_{a}} \frac{\partial p_{a}}{\partial \theta_{j}}, \\
& \frac{\partial p_{a}}{\partial \theta_{j}}=-\frac{e^{\theta_{a}} e^{\theta_{j}}}{\left(1+\sum_{b=1}^{K-1} e^{\theta_{b}}\right)^{2}}=-p_{j} p_{a} \quad(a=1, \ldots, K-1 ; a \neq j),  \tag{S.2}\\
& \frac{\partial p_{j}}{\partial \theta_{j}}=p_{j}\left(1-p_{j}\right) \equiv p_{j} q_{j}, \frac{\partial p_{K}}{\partial \theta_{j}}=-p_{j} p_{K} \quad(j=1, \ldots, K-1) .
\end{align*}
$$

From (S.2),

$$
\begin{align*}
\frac{\partial \bar{l}}{\partial \theta_{j}} & =n^{-1} \sum_{i=1}^{n}\left(-\sum_{a=1}^{K-1} \frac{y_{i a}}{p_{a}} p_{a} p_{j}+\frac{y_{i j}}{p_{j}} p_{j}-\frac{y_{i K}}{p_{K}} p_{j} p_{K}\right) \\
& =n^{-1} \sum_{i=1}^{n} y_{i j}-n^{-1} \sum_{i=1}^{n} \sum_{a=1}^{K} y_{i a} p_{j}  \tag{S.3}\\
& \equiv \bar{y}_{j}-p_{j}, \\
\frac{\partial^{2} \bar{l}}{\partial \theta_{j}^{2}} & =-\frac{\partial p_{j}}{\partial \theta_{j}}=-p_{j} q_{j} \quad(j=1, \ldots, K-1), \\
\frac{\partial^{2} \bar{l}}{\partial \theta_{j} \partial \theta_{k^{*}}} & =p_{j} p_{k^{*}} \quad\left(j, k^{*}=1, \ldots, K-1 ; j \neq k^{*}\right) .
\end{align*}
$$

Then, the population information matrix per observation becomes

$$
\mathbf{I}_{0}=\left[\begin{array}{cccc}
p_{1} q_{1} & -p_{1} p_{2} & \cdots & -p_{1} p_{K-1}  \tag{S.4}\\
-p_{2} p_{1} & p_{2} q_{2} & \cdots & -p_{2} p_{K-1} \\
\vdots & \vdots & \ddots & \vdots \\
-p_{K-1} p_{1}-p_{K-1} p_{2} & \cdots & p_{K-1} q_{K-1}
\end{array}\right]=\operatorname{cov}\left(\mathbf{Y}_{(K-1)}\right)
$$

with $\mathbf{Y}_{(K-1)}=\left(Y_{1}, \ldots, Y_{K-1}\right)^{\prime}$. Note that (S.4) is also given from the property of the canonical parameters in the exponential family. The $(K-1) \times(K-1)$ matrix $\mathbf{I}_{0}$ is also denoted by $\mathbf{I}_{0(K-1)}$ for clarity.

## Lemma 1.

$$
\begin{equation*}
\left|\mathbf{I}_{0(K-1)}\right|=p_{1} p_{2} \cdots p_{K} \tag{S.5}
\end{equation*}
$$

Proof. The result is derived by induction. Assume that $p_{j}>0(j=1, \ldots, K)$. When $K=2, \quad \mathbf{I}_{0(1)}=p_{1} q_{1}=p_{1} p_{2}$, which shows that (S.5) holds. Suppose that when $K=J$, (S.5) holds. Write $\mathbf{I}_{0(J)}=\left[\begin{array}{rc}\mathbf{I}_{0(J-1)} & -\mathbf{p}_{(J-1)} p_{J} \\ -\mathbf{p}_{(J-1)}{ }^{\prime} p_{J} & p_{J} q_{J}\end{array}\right]$, where $\mathbf{p}_{(J-1)}=\left(p_{1}, \ldots, p_{J-1}\right)^{\prime}$. Since $\left|\mathbf{I}_{0(J-1)}\right|=p_{1} p_{2} \cdots p_{J}>0$ by assumption, $\mathbf{I}_{0(J-1)}$ has its inverse.
Consequently, using the formula of the determinant of a partitioned matrix,
$\operatorname{det}\left[\begin{array}{cc}\mathbf{A} & \mathbf{b} \\ \mathbf{b}^{\prime} & c\end{array}\right]=|\mathbf{A}|\left(c-\mathbf{b}^{\prime} \mathbf{A}^{-1} \mathbf{b}\right)$ when $\mathbf{A}$ is nonsingular, it follows that

$$
\begin{equation*}
\left|\mathbf{I}_{0(J)}\right|=\left|\mathbf{I}_{0(J-1)}\right|\left(p_{J} q_{J}-p_{J}^{2} \mathbf{p}_{(J-1)}{ }^{\prime} \mathbf{I}_{0(J-1)}^{-1} \mathbf{p}_{(J-1)}\right) \tag{S.6}
\end{equation*}
$$

where

$$
\begin{align*}
\mathbf{I}_{0(J-1)}^{-1} & =\left\{\operatorname{diag}\left(\mathbf{p}_{(J-1)}\right)-\mathbf{p}_{(J-1)} \mathbf{p}_{(J-1)}\right\}^{-1} \\
& =\operatorname{diag}^{-1}\left(\mathbf{p}_{(J-1)}\right)+\frac{\operatorname{diag}^{-1}\left(\mathbf{p}_{(J-1)}\right) \mathbf{p}_{(J-1)} \mathbf{p}_{(J-1)}{ }^{\prime} \operatorname{diag}^{-1}\left(\mathbf{p}_{(J-1)}\right)}{1-\mathbf{p}_{(J-1)}{ }^{\prime} \operatorname{diag}^{-1}\left(\mathbf{p}_{(J-1)}\right) \mathbf{p}_{(J-1)}}  \tag{S.7}\\
& =\operatorname{diag}^{-1}\left(\mathbf{p}_{(J-1)}\right)+\frac{\mathbf{1}_{(J-1)} \mathbf{1}_{(J-1)}^{\prime}}{1-\mathbf{p}_{(J-1)}^{\prime} \mathbf{1}_{(J-1)}}
\end{align*}
$$

which gives

$$
\begin{align*}
\mid \mathbf{I}_{0(J)} & =\left|\mathbf{I}_{0(J-1)}\right|\left[p_{J} q_{J}-p_{J}^{2}\left\{\mathbf{p}_{(J-1)}^{\prime} \mathbf{1}_{(J-1)}+\frac{\left(\mathbf{p}_{(J-1)}^{\prime} \mathbf{1}_{(J-1)}\right)^{2}}{1-\mathbf{p}_{(J-1)}^{\prime} \mathbf{1}_{(J-1)}}\right\}\right] \\
& =\left|\mathbf{I}_{0(J-1)}\right|\left(p_{J} q_{J}-\frac{p_{J}^{2} \mathbf{p}_{(J-1)}{ }^{\prime} \mathbf{1}_{(J-1)}}{1-\mathbf{p}_{(J-1)}^{\prime} \mathbf{1}_{(J-1)}}\right) \\
& =\left|\mathbf{I}_{0(J-1)}\right| p_{J} \frac{1-\mathbf{p}_{(J-1)}^{\prime} \mathbf{1}_{(J-1)}-p_{J}}{1-\mathbf{p}_{(J-1)} \mathbf{1}_{(J-1)}}  \tag{S.8}\\
& =p_{1} p_{2} \cdots p_{J}\left(1-p_{1}-\ldots-p_{J}\right)
\end{align*}
$$

which shows that (S.5) holds when $K=J+1$. When $p_{1} p_{2} \cdots p_{J}=0$, from (S.4) with $K=J+1$, at least one of the rows/columns of $\mathbf{I}_{0(J)}$ is zero and consequently, $\left|\mathbf{I}_{0(J)}\right|=0$, which shows that (S.5) holds also for the singular case. Q.E.D.

## 2. The Jeffreys prior

The $\log$ prior derivatives evaluated at the population values are

$$
\begin{equation*}
\mathbf{q}_{0}^{*}=\frac{1}{2} \frac{\partial \log \left|\mathbf{I}_{0(K-1)}\right|}{\partial \boldsymbol{\theta}_{0}}=\frac{1}{2} \frac{\partial}{\partial \boldsymbol{\theta}_{0}} \sum_{j=1}^{K} \log p_{j}=\frac{1}{2} \sum_{j=1}^{K} \frac{1}{p_{j}} \frac{\partial p_{j}}{\partial \boldsymbol{\theta}_{0}}, \tag{S.9}
\end{equation*}
$$

where

$$
\begin{aligned}
\frac{\partial p_{j}}{\partial \boldsymbol{\theta}_{0}} & =\left(-p_{1} p_{j},-p_{2} p_{j}, \ldots, p_{j} q_{j}, \ldots,-p_{K-1} p_{j}\right)^{\prime} \\
& =-p_{j} \mathbf{p}_{(K-1)}+\left(\mathbf{0}^{\prime}, p_{j}, \mathbf{0}^{\prime}\right)^{\prime}(j=1, \ldots, K-1), \\
\frac{\partial p_{K}}{\partial \boldsymbol{\theta}_{0}} & =\left(-p_{1} p_{K},-p_{2} p_{K}, \ldots,-p_{j} p_{K}, \ldots,-p_{K-1} p_{K}\right)^{\prime} \\
& =-p_{K} \mathbf{p}_{(K-1)}
\end{aligned}
$$

Consequently, (S.9) becomes

$$
\begin{equation*}
\mathbf{q}_{0}^{*}=\frac{1}{2}\left(\mathbf{1}_{(K-1)}-K \mathbf{p}_{(K-1)}\right) . \tag{S.11}
\end{equation*}
$$

When $K=2$, (S.11) becomes $\left(1-2 p_{1}\right) / 2$, which is also given by $\frac{\partial \log \left(p_{1} q_{1}\right)^{1 / 2}}{\partial \theta_{1}}=\frac{1}{2 p_{1} q_{1}} \frac{\partial p_{1} q_{1}}{\partial \theta_{1}}=\frac{1-2 p_{1}}{2}$. Note that $\mathbf{q}_{0}^{*}=\mathbf{0}$ when $\mathbf{p}_{(K-1)}=1 / K$ and $p_{K}=1 / K$ or when the proportions $p_{j}(j=1, \ldots, K)$ are equal. When $K=2$, this holds with $p_{1}=0.5$.

## Lemma 2.

$$
\begin{equation*}
\boldsymbol{\alpha}_{\mathrm{ML} 1}=-0.5\left(p_{1}^{-1}, \ldots, p_{K-1}^{-1}\right)^{\prime}+0.5 p_{K}^{-1} \mathbf{1}_{(K-1)} . \tag{S.12}
\end{equation*}
$$

Proof. Since

$$
\begin{equation*}
\hat{\boldsymbol{\theta}}_{\mathrm{ML}}=\left\{\log \left(\hat{p}_{1} / \hat{p}_{K}\right), \ldots, \log \left(\hat{p}_{K-1} / \hat{p}_{K}\right)\right\}^{\prime} \tag{S.13}
\end{equation*}
$$

with $\hat{p}_{j}=n^{-1} \sum_{i=1}^{n} y_{i j}(j=1, \ldots, K)$,

$$
\begin{align*}
\hat{\boldsymbol{\theta}}_{\mathrm{ML}}= & \boldsymbol{\theta}_{0}+\frac{\partial \boldsymbol{\theta}_{0}}{\partial \mathbf{p}_{(K-1)}}\left(\hat{\mathbf{p}}_{(K-1)}-\mathbf{p}_{(K-1)}\right) \\
& +\frac{1}{2} \frac{\partial^{2} \boldsymbol{\theta}_{0}}{\left(\partial \mathbf{p}_{(K-1)}\right)^{<2>}}\left(\hat{\mathbf{p}}_{(K-1)}-\mathbf{p}_{(K-1)}\right)^{<2>}  \tag{S.14}\\
& +\frac{1}{6} \frac{\partial^{3} \boldsymbol{\theta}_{0}}{\left(\partial \mathbf{p}_{(K-1)} I^{<3>}\right.}\left(\hat{\mathbf{p}}_{(K-1)}-\mathbf{p}_{(K-1)}\right)^{<3>}+O_{p}\left(n^{-2}\right),
\end{align*}
$$

where $\hat{\mathbf{p}}_{(K-1)}=\left(\hat{p}_{1}, \ldots, \hat{p}_{K-1}\right)^{\prime}$,

$$
\left(\frac{\partial \boldsymbol{\theta}_{0}}{\partial \mathbf{p}_{(K-1)}{ }^{\prime}}\right)_{j k^{*}}=\frac{\delta_{j k^{*}}}{p_{j}}+\frac{1}{1-\mathbf{p}_{(K-1)} \mathbf{1}_{(K-1)}} \quad\left(j, k^{*}=1, \ldots, K-1\right)
$$

which gives

$$
\begin{equation*}
\frac{\partial \boldsymbol{\theta}_{0}}{\partial \mathbf{p}_{(K-1)}{ }^{\prime}}=\operatorname{diag}\left(p_{1}^{-1}, \ldots, p_{K-1}^{-1}\right)+\frac{\mathbf{1}_{(K-1)} \mathbf{1}_{(K-1)}^{\prime}}{1-\mathbf{p}_{(K-1)} \mathbf{1}_{(K-1)}}=\mathbf{I}_{0(K-1)}^{-1}, \tag{S.15}
\end{equation*}
$$

which also comes from Subsection A. 1 of the appendix.

$$
\left.\begin{array}{l}
\frac{\partial^{2} \boldsymbol{\theta}_{0}}{\partial p_{j} \partial p_{k^{*}}}=\left(\mathbf{0}^{\prime},-\delta_{j k^{*}} p_{j}^{-2}, \mathbf{0}\right)^{\prime}+\frac{\mathbf{1}_{(K-1)}}{\left(1-\mathbf{p}_{(K-1)} \mathbf{1}_{(K-1)}\right)^{2}} \\
 \tag{S.16}\\
=- \\
\delta_{j k^{*}} p_{j}^{-2} \mathbf{e}_{(j)}+p_{K}^{-2} \mathbf{1}_{(K-1)},
\end{array}\right\} \begin{aligned}
& \frac{\partial^{3} \boldsymbol{\theta}_{0}}{\partial p_{j} \partial p_{k^{*}} \partial p_{l^{*}}}=\delta_{j k^{*}} \delta_{k^{*} l^{*}} 2 p_{j}^{-3} \mathbf{e}_{(j)}+2 p_{K}^{-3} \mathbf{1}_{(K-1)}\left(j, k^{*}, l^{*}=1, \ldots, K-1\right) .
\end{aligned}
$$

From the above results,

$$
\begin{align*}
\hat{\boldsymbol{\theta}}_{\mathrm{ML}}= & \boldsymbol{\theta}_{0}+\left\{p_{1}^{-1}\left(\hat{p}_{1}-p_{1}\right), \ldots, p_{K-1}^{-1}\left(\hat{p}_{K-1}-p_{K-1}\right)\right\}^{\prime} \\
& \quad+p_{K}^{-1} \mathbf{1}_{(K-1)}\left(\hat{\mathbf{p}}_{(K-1)}-\mathbf{p}_{(K-1)}\right) \mathbf{1}_{(K-1)} \\
+\frac{1}{2}[ & -\left\{p_{1}^{-2}\left(\hat{p}_{1}-p_{1}\right)^{2}, \ldots, p_{K-1}^{-2}\left(\hat{p}_{K-1}-p_{K-1}\right)^{2}\right\}^{\prime} \\
& \left.+p_{K}^{-2}\left(\mathbf{1}_{(K-1)}\right)^{<2>}\left(\hat{\mathbf{p}}_{(K-1)}-\mathbf{p}_{(K-1)}\right)^{<2>} \mathbf{1}_{(K-1)}\right] \\
+\frac{1}{3}[ & \left\{p_{1}^{-3}\left(\hat{p}_{1}-p_{1}\right)^{3}, \ldots, p_{K-1}^{-3}\left(\hat{p}_{K-1}-p_{K-1}\right)^{3}\right\}^{\prime}  \tag{S.17}\\
& \left.+p_{K}^{-3}\left(\mathbf{1}_{(K-1)}\right)^{<3>}\left(\hat{\mathbf{p}}_{(K-1)}-\mathbf{p}_{(K-1)}\right)^{<3>} \mathbf{1}_{(K-1)}\right]+O_{p}\left(n^{-3}\right) .
\end{align*}
$$

From (S.17),

$$
\begin{align*}
\left(\boldsymbol{\alpha}_{\mathrm{ML1}}\right)_{j} & =\frac{1}{2}\left\{-p_{j}^{-2}\left(\mathbf{I}_{0(K-1)}\right)_{j j}+p_{K}^{-2} \sum_{a, b=1}^{K-1}\left(\mathbf{I}_{0(K-1)}\right)_{a b}\right\} \\
& =\frac{1}{2}\left(-\frac{1-p_{j}}{p_{j}}+\frac{1-p_{K}}{p_{K}}\right)  \tag{S.18}\\
& =\frac{1}{2}\left(-\frac{1}{p_{j}}+\frac{1}{p_{K}}\right)=\frac{p_{j}-p_{K}}{2 p_{j} p_{K}} \quad(j=1, \ldots, K-1),
\end{align*}
$$

where

$$
\begin{align*}
\sum_{a, b=1}^{K-1}\left(\mathbf{I}_{0(K-1)}\right)_{a b} & =\mathbf{1}_{(K-1)} '^{\prime} \mathbf{I}_{0(K-1)} \mathbf{1}_{(K-1)} \\
& =\mathbf{1}_{(K-1)}{ }^{\prime}\left(\mathbf{p}_{(K-1)}-\mathbf{p}_{(K-1)} \mathbf{p}_{(K-1)}{ }^{\prime} \mathbf{1}_{(K-1)}\right)  \tag{S.19}\\
& =\mathbf{1}_{(K-1)}{ }^{\prime} p_{K} \mathbf{p}_{(K-1)}=p_{K}\left(1-p_{K}\right)
\end{align*}
$$

is used. (S.18) gives (S.12). Q.E.D.
Note that the term (1/3)[•] in (S.17) is unnecessary to have the result, but is included for illustration.

From Lemma 2, we have

$$
\begin{align*}
& n \operatorname{acov}\left\{\left(\hat{\boldsymbol{\alpha}}_{\mathrm{ML} 1}\right)_{j}, \hat{\boldsymbol{\theta}}_{\mathrm{ML}}{ }^{\prime}\right\}=\frac{1}{2}\left\{\frac{\partial}{\partial \mathbf{p}_{(K-1)}}\left(-\frac{1}{p_{j}}+\frac{1}{p_{K}}\right)\right\} \mathbf{I}_{0(K-1)} \frac{\partial \boldsymbol{\theta}_{0}{ }^{\prime}}{\partial \mathbf{p}_{(K-1)}} \\
& \quad=\frac{1}{2}\left\{\left(\mathbf{0}^{\prime}, p_{j}^{-2}, \mathbf{0}^{\prime}\right)+p_{K}^{-2} \mathbf{1}_{(K-1)}{ }^{\prime}\right\} \mathbf{I}_{0(K-1)} \mathbf{I}_{0(K-1)}^{-1}  \tag{S.20}\\
& \quad=\frac{1}{2}\left(p_{j}^{-2} \mathbf{e}_{(j)}+p_{K}^{-2} \mathbf{1}_{(K-1)}\right)^{\prime}>\mathbf{0}^{\prime},
\end{align*}
$$

which gives

$$
\begin{equation*}
n \operatorname{acov}\left(\hat{\boldsymbol{\alpha}}_{\mathrm{ML} 1}, \hat{\boldsymbol{\theta}}_{\mathrm{ML}}^{\prime} '\right)=\frac{1}{2}\left\{\operatorname{diag}\left(p_{1}^{-2}, \ldots, p_{K-1}^{-2}\right)+p_{K}^{-2} \mathbf{1}_{(K-1)} \mathbf{1}_{(K-1)}^{\prime}\right\} . \tag{S.21}
\end{equation*}
$$

### 2.1 Linear predictor with the Jeffreys prior

Using Lemma 2 and (S.20), Result 5 gives

$$
\begin{aligned}
k_{\min } & =\left(\mathbf{p}^{*} ' \boldsymbol{\alpha}_{\mathrm{ML} 1}\right)^{-2} \mathbf{p}^{*} ' n \operatorname{acov}\left(\hat{\boldsymbol{\alpha}}_{\mathrm{ML} 1}, \hat{\boldsymbol{\theta}}_{\mathrm{ML}} '\right) \mathbf{p}^{*}+1 \\
= & 2\left\{-\mathbf{p}^{*}\left(p_{1}^{-1}, \ldots, p_{K-1}^{-1}\right)+p_{K}^{-1} \mathbf{p}^{*} \mathbf{1}_{(K-1)}\right\}^{-2} \\
& \times\left\{\mathbf{p}^{*} ' \operatorname{diag}\left(p_{1}^{-2}, \ldots, p_{K-1}^{-2}\right) \mathbf{p}^{*}+p_{K}^{-2}\left(\mathbf{p}^{*} \mathbf{1}_{(K-1)}\right)^{2}\right\}+1 \\
& >1
\end{aligned}
$$

### 2.2 TMSE with the Jeffreys prior

Similarly, Result 6 yields

$$
\begin{align*}
k_{\min } & =\left(\boldsymbol{\alpha}_{\mathrm{ML} 1}{ }^{\prime} \boldsymbol{\alpha}_{\mathrm{ML} 1}\right)^{-1} \operatorname{tr}\left\{n \operatorname{acov}\left(\hat{\boldsymbol{\alpha}}_{\mathrm{ML} 1}, \hat{\boldsymbol{\theta}}_{\mathrm{ML}}{ }^{\prime}\right)\right\}+1 \\
& =2\left\{\sum_{j=1}^{K-1}\left(-\frac{1}{p_{j}}+\frac{1}{p_{K}}\right)^{2}\right\}^{-1}\left(\sum_{j=1}^{K-1} \frac{1}{p_{j}^{2}}+\frac{K-1}{p_{K}^{2}}\right)+1 \tag{S.23}
\end{align*}
$$

$>3$ (for the inequality see Result 9).

## 3. The Gaussian prior

The density of the Gaussian prior is defined as

$$
\begin{equation*}
f(\boldsymbol{\theta}) \propto \exp \left(-\boldsymbol{\theta}^{\prime} \boldsymbol{\theta} / 2\right) \tag{S.24}
\end{equation*}
$$

giving $\mathbf{q}_{0}^{*}=-\boldsymbol{\theta}_{0}$.
Under correct model specification, from (2.3) and (2.4) $\quad \mathbf{A}_{\mathrm{G} \mid \mathrm{ML} \Delta 2}$ or $\mathbf{A}_{\mathrm{W} \mid \mathrm{ML} \Delta 2}$ by the Gaussian prior is

$$
\begin{equation*}
\mathbf{A}_{\mathrm{G} \mid \mathrm{ML} \Delta 2}=n \mathrm{E}_{\theta}\left(\mathbf{L}^{(\mathrm{W})} \mathbf{l}_{0}^{(1)} \mathbf{\Lambda}^{(1)}+\mathbf{\Lambda}^{(1)} \mathbf{l}_{0}^{(1)} \mathbf{L}^{(\mathrm{W})}{ }^{\prime}\right) \tag{S.25}
\end{equation*}
$$

where

$$
\begin{equation*}
\mathbf{L}^{(\mathrm{W})}=-\left(-\hat{\mathbf{I}}_{(K-1)}^{-1} \hat{\mathbf{q}}^{*}+\mathbf{I}_{0(K-1)}^{-1} \mathbf{q}_{0}^{*}\right)=\hat{\mathbf{I}}_{(K-1)}^{-1} \hat{\mathbf{q}}^{*}-\mathbf{I}_{0(K-1)}^{-1} \mathbf{q}_{0}^{*} \tag{S.26}
\end{equation*}
$$

$\hat{\mathbf{I}}_{(K-1)}$ and $\hat{\mathbf{q}}^{*}$ are $\mathbf{I}_{0(K-1)}$ and $\mathbf{q}_{0}^{*}$, respectively with $\boldsymbol{\theta}_{0}$ replaced by $\hat{\boldsymbol{\theta}}_{\mathrm{ML}}$. (S.25) become

$$
\begin{equation*}
\mathbf{A}_{\mathrm{G} \mid \mathrm{ML} \Delta 2}=\frac{\partial \mathbf{I}_{0(K-1)}^{-1} \mathbf{q}_{0}^{*}}{\partial \boldsymbol{\theta}_{0}{ }^{\prime}} \mathbf{A}_{\mathrm{ML} 2}+\mathbf{A}_{\mathrm{ML} 2} \frac{\partial \mathbf{q}_{0}^{*} \cdot \mathbf{I}_{0(K-1)}^{-1}}{\partial \boldsymbol{\theta}_{0}} \tag{S.27}
\end{equation*}
$$

where $\mathbf{A}_{\mathrm{ML} 2}=\mathbf{I}_{0(K-1)}^{-1}$ and

$$
\begin{align*}
& \frac{\partial \mathbf{I}_{0(K-1)}^{-1} \mathbf{q}_{0}^{*}}{\partial\left(\boldsymbol{\theta}_{0}\right)_{j}}=-\frac{\partial \mathbf{I}_{0(K-1)}^{-1} \boldsymbol{\theta}_{0}}{\partial\left(\boldsymbol{\theta}_{0}\right)_{j}} \\
& =-\left[\frac{\partial}{\partial\left(\boldsymbol{\theta}_{0}\right)_{j}}\left\{\operatorname{diag}\left(p_{1}^{-1}, \ldots, p_{K-1}^{-1}\right)+p_{K}^{-1} \mathbf{1}_{(K-1)} \mathbf{1}_{(K-1)}\right\}\right] \boldsymbol{\theta}_{0}-\left(\mathbf{I}_{0(K-1)}^{-1}\right)_{j} \\
& =\left\{\begin{array}{l}
\left.\operatorname{diag}\left(p_{1}^{-2} \frac{\partial p_{1}}{\partial\left(\boldsymbol{\theta}_{0}\right)_{j}}, \ldots, p_{K-1}^{-2} \frac{\partial p_{K-1}}{\partial\left(\boldsymbol{\theta}_{0}\right)_{j}}\right)+p_{K}^{-2} \frac{\partial p_{K}}{\partial\left(\boldsymbol{\theta}_{0}\right)_{j}} \mathbf{1}_{(K-1)} \mathbf{1}_{(K-1)} '^{\prime}\right\} \boldsymbol{\theta}_{0} \\
\quad-\left(\mathbf{I}_{0(K-1)}^{-1}\right)_{j}
\end{array}\right. \\
& =\left[\operatorname{diag}\left\{-p_{1}^{-2} p_{1} p_{j}, \ldots, p_{j}^{-2} p_{j}\left(1-p_{j}\right), \ldots,-p_{K-1}^{-2} p_{K-1} p_{j}\right\}\right. \\
& \left.\left.\quad-p_{K}^{-2} p_{K} p_{j} \mathbf{1}_{(K-1)} \mathbf{1}_{(K-1)}^{\prime}\right] \mathbf{\theta}_{0}-\left(\mathbf{I}_{(K-1)}^{-1}\right)\right)_{j} \\
& =\left\{-p_{j} \operatorname{diag}\left(p_{1}^{-1}, \ldots, p_{K-1}^{-1}\right)+\operatorname{diag}\left(\mathbf{0}^{\prime}, p_{j}^{-1}, \mathbf{0}^{\prime}\right)\right. \\
& \left.\quad-p_{K}^{-1} p_{j} \mathbf{1}_{(K-1)} \mathbf{1}_{(K-1)}{ }^{\prime}\right\} \boldsymbol{\theta}_{0}-\left(\mathbf{I}_{0(K-1)}^{-1}\right)_{j} \\
& (j=1, \ldots, K-1) . \tag{S.28}
\end{align*}
$$

### 3.1 Linear predictor with the Gaussian prior

Result 3 with the above results gives

$$
\begin{equation*}
k_{\min }=-\frac{\mathbf{p}^{*} \cdot \mathbf{A}_{\mathrm{G} \mid \mathrm{ML} \Delta 2} \mathbf{p}^{*}}{2\left(\mathbf{p}^{*} \cdot \mathbf{I}_{0(K-1)}^{-1} \boldsymbol{\theta}_{0}\right)^{2}}+\frac{\mathbf{p}^{*} \cdot \boldsymbol{\alpha}_{\mathrm{ML} 1}}{\mathbf{p}^{*} \mathbf{I}_{0(K-1)}^{-1} \boldsymbol{\theta}_{0}} . \tag{S.29}
\end{equation*}
$$

### 3.2 TMSE with the Gaussian prior

Similarly, Result 4 gives

$$
\begin{equation*}
k_{\min }=\frac{1}{2}\left(\boldsymbol{\theta}_{0}^{\prime} \mathbf{I}_{0(K-1)}^{-2} \boldsymbol{\theta}_{0}\right)^{-1}\left\{-\operatorname{tr}\left(\mathbf{A}_{\mathrm{G} \mid \mathrm{ML} \Delta 2}\right)+2 \boldsymbol{\theta}_{0}{ }^{\prime} \mathbf{I}_{0(K-1)}^{-1} \boldsymbol{\alpha}_{\mathrm{ML} 1}\right\} \tag{S.30}
\end{equation*}
$$

4. The largest variance of the non-negative quantities whose sum is fixed Let $p_{j}(j=1, \ldots, K)$ with fixed $K$ be non-negative quantities, which vary with their sum being fixed. Suppose that the sum is 1 without loss of generality. Then, the variance of $p_{1}, \ldots, p_{K}$ denoted by $\operatorname{var}(p)$ is given by

$$
\begin{equation*}
K \operatorname{var}(p)=\sum_{j=1}^{K} p_{j}^{2}-K^{-1}\left(\sum_{j=1}^{K} p_{j}\right)^{2}=\sum_{j=1}^{K} p_{j}^{2}-K^{-1} \tag{S.31}
\end{equation*}
$$

So, the problem of maximizing the $\operatorname{var}(p)$ reduces to that of $\sum_{j=1}^{K} p_{j}^{2}$. In the case of $K=2, \quad \sum_{j=1}^{2} p_{j}^{2}=p_{1}^{2}+p_{2}^{2}=p_{1}^{2}+\left(1-p_{1}\right)^{2}$, whose largest value is given when $p_{1}=0$ or 1 . The smallest variance 0 is given when $p_{1}=p_{2}=0.5$. Note that $p_{1}^{2}+p_{2}^{2}$ is the square of the radius of the circle whose center is the origin in the $\left(p_{1}, p_{2}\right)$ plane. Since $p_{1} \geq 0, p_{2} \geq 0$ and $p_{1}+p_{2}=1$, possible values of $p_{1}^{2}+p_{2}^{2}$ are those on the line segment connecting $(0,1)$ and $(1,0)$ in Figure 1. The value $p_{1}^{2}+p_{2}^{2}$ is given by the square of the radius of the circle which has point(s) on the line segment in the first quadrant including $(0,1)$ and $(1,0)$. From Figure 1 , it is obvious that the largest value is given when $\left(p_{1}, p_{2}\right)$ $=(0,1)$ or $(1,0)$ and that the smallest value is given when $p_{1}=p_{1}=0.5$.

Generalizing the above result to the $K$-dimensional space with $K \geq 3$, the line segment becomes a portion of the $(K-1)$-dimensional hyperplane satisfying $p_{1}+\ldots+p_{K}=1$ and $p_{j} \geq 0(j=1, \ldots, K)$. The problem is to have the largest radius of the ball whose center is the origin and whose surface has point(s) on the plane. Since the plane is restricted to be in the first (generalized) quadrant $\left(1 \geq p_{j} \geq 0 ; j=1, \ldots, K\right)$, the ball with the largest radius has $K$ points $\left(p_{1}, p_{2}, \ldots, p_{K}\right)=(1,0, \ldots, 0),(0,1,0, \ldots, 0), \ldots,(0, \ldots, 0,1)$ on the plane. This gives the largest variance

$$
\begin{equation*}
K^{-1} \sum_{j=1}^{K} p_{j}^{2}-K^{-2}=K^{-1}-K^{-2} \tag{S.32}
\end{equation*}
$$

The smallest variance 0 is given when $p_{1}=\ldots=p_{K}=K^{-1}$.
When the sum is $c$ rather than 1 , the largest variance becomes $c^{2}\left(K^{-1}-K^{-2}\right)$.


Figure 1. A geometric interpretation of the problem maximizing the variance of non-negative quantities when the mean is fixed

## Reference

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